

KPR Institute of Engineering and Technology

Learn Beyond

(Autonomous, NAAC "A")

Avinashi Road, Arasur, Coimbatore.

Great Place To Work® Certified

M.E. – CAD / CAM
Curriculum and Syllabi
(Regulations – 2023)





I. Vision and Mission of the Institute

Vision

To become a premier institute of academic excellence by imparting technical, intellectual and professional skills to students for meeting the diverse needs of the industry, society, the nation and the world at large.

Mission

- Commitment to offer value—based education and enhancement of practical skills
- Continuous assessment of teaching and learning processes through scholarly activities
- Enriching research and innovation activities in collaboration with industry and institutes of repute
- Ensuring the academic processes to uphold culture, ethics and social responsibilities

II. Vision and Mission of the Department

Vision

To produce globally competent mechanical engineers to meet the changing needs of industries through innovative academic processes, research and value—based education

Mission

- Provide fundamental and skill—based education in mechanical engineering through innovative practicesin teaching and leaning
- Establishing centre of excellence in collaborate with reputed industries, professional bodies and research laboratories
- Promote entrepreneurship with leadership qualities, ethics human values for society at large

III. Program Educational Objectives (PEOs)

Graduates of BE Mechanical Engineering four years after graduation will:

PEO1: Excel in their professional career with competencies in the field of mechanical and allied engineering

PEO2: Apply modern research and simulation tools to solve industrial and societal needs

PEO3: Practice professional and ethical values in respective organizations and society

Program Outcomes (POs)

Graduates will be able to:

PO1: Identify, formulate and solve engineering problems using modern engineering and computer

aided tools of set to best

PO2: Conduct experiments analyze and interpret data in the area of design and manufacturing

PO3: Demonstrate skills to provide solutions for multidisciplinary problems using modern technologies

PO4: Independently carry out research /investigation and development work to solve practical problems

PO5: Write and present a substantial technical report/document effectively

PO6: Develop the art of self-learning and ability for life-long learning



IV.Program Specific Outcomes (PSOs)

A Graduate of Mechanical Engineering should:

PSO 1: Design, develop and implement advanced mechanical systems by applying engineering principles for improved performance and less human effort

PSO 2: Apply quality tools to ensure quality, articulate maintenance principles and demonstrate managerial skills to comprehend the mechanical engineering processes, products and services VI. PEO/PO Mapping

Following three levels of correlation should be used:

- 1: Low
- 2: Medium
- 3: High

PEO/PO	PO1	PO2	PO3	PO4	PO5	PO6
PEO1	3	3	3	3	2	2
PEO2	3	3	3	3	2	3
PEO3	3	3	3	3	3	3

M.E. CAD/CAM ENGINEERING REGULATIONS – 2023

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Centre for

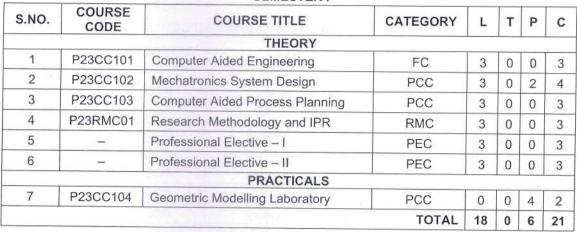
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Academic Courses

CHOICE BASED CREDIT SYSTEM

CURRICULUM FOR I TO IV SEMESTERS

SEMESTER I



SEMESTER II

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
		THEORY				_	_
1	P23CC201	Advance Finite Element Method	PCC	3	0	2	4
2	P23CC202	Additive Manufacturing and Tooling	PCC	3	0	0	3
3	P23CC203	Product Life Cycle Management	PCC	3	0	0	3
4	P23CC204	Design for Sustainability	PCC	3	0	0	3
5	_	Professional Elective - III	PEC	3	0	0	3
6		Professional Elective – IV	PEC	3	0	0	3
		PRACTICALS		98		878	- 3
7	P23CC205	Technical Seminar	EEC	0	0	4	2
			TOTAL	18	0	6	21

SEMESTER III

S.NO.	COURSE CODE	COURSE TITLE	CATEGORY	L	Т	Р	С
		THEORY					-
1		Professional Elective – V	PEC	3	0	0	3
2	-	Professional Elective – VI	PEC	3	0	0	3
		PRACTICALS					
3	P23CC301	Project Work Phase - I	EEC	0	0	12	6
			TOTAL	6	0	12	12

SEMESTER IV

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
	1.00	PRACTICALS					
1	P23CC401	Project Work Phase - II	EEC	0	0	24	12
2	P23CCI01	Industrial Training/Internship	EEC	0	0	0	2
		5	TOTAL	0	0	24	14

3



LIST OF COURSES BASED ON ITS CATEGORY

FOUNDATION COURSES (FC)

S.NO.	COURSE CODE	COURSE TITLE	CATEGORY	L	T	Р	С
1	P23CC101	Computer Aided Engineering	FC	3	0	0	3

PROFESSIONAL CORE COURSES (PCC)

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
		THEORY					
1	P23CC102	Mechatronics System Design	PCC	3	0	2	4
2	P23CC103	Computer Aided Process Planning	PCC	3	0	0	3
3	P23CC201	Advance Finite Element Method	PCC	3	0	2	4
4	P23CC202	Additive Manufacturing and Tooling	PCC	3	0	0	3
5	P23CC203	Product Life Cycle Management	PCC	3	0	0	3
6	P23CC204	Design for Sustainability	PCC	3	0	0	3
7	P23CC104	Geometric Modelling Laboratory	PCC	0	0	4	2

PROFESSIONAL ELECTIVES COURSES (PEC)

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
1	P23CCP01	Design of Material Handling Systems	PEC	3	0	0	3
2	P23CCP02	Mechanical Behaviour of Materials	PEC	3	0	0	3
3	P23CCP03	Optimization Techniques in Design	PEC	3	0	0	3
4	P23CCP04	Quality Engineering	PEC	3	0	0	3
5	P23CCP05	CNC Technology and Programming		3	0	0	3
6	P23CCP06	Sensors and Instrumentation	PEC	3	0	0	3
7	P23CCP07	Supply Chain Management	PEC	3	0	0	3
8	P23CCP08	Composite Materials and Mechanics	PEC '	3	0	0	3
9	P23CCP09	Design for Manufacturing Systems	PEC	3	0	0	3
10	P23CCP10	Performance Modelling and Analysis of Manufacturing Systems	PEC	3	0	0	3
11	P23CCP11	Industrial Robotics	PEC	3	0	0	3
12	P23CCP12	MEMS and NEMS	PEC	3	0	0	3
13	P23CCP13	Computational Fluid Dynamics	PEC	3	0	0	3
14	P23CCP14	Reliability in Engineering Systems	PEC	3	0	0	3
15	P23CCP15	Project Management	PEC	3	0	0	3
16	P23CCP16	Embedded System Design	PEC	3	0	0	3
17	P23CCP17	Micro and Smart Systems	PEC	3	0	0	3
18	P23CCP18	Internet of things in Manufacturing	PEC	3	0	0	3

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RESEARCH METHODOLOGY & IPR COURSES (RMC)

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
1	P23RMC01	Research Methodology and IPR	RMC	3	0	0	3

EMPLOYABILITY ENHANCEMENT COURSES (EEC)

S.NO.	COURSE	COURSE TITLE	CATEGORY	L	Т	Р	С
1	P23CC206	Technical Seminar	EEC	0	0	4	2
2	P23CC301	Project Work - Phase I	EEC	0	0	12	6
3	P23CC401	Project Work - Phase II	EEC	0	0	24	12
4	P23CCI01	Industrial Training / Internship	EEC	0	0	0	2

VIII. Scheme of Credit distribution - Summary

S. No	Stream	Cı	edits/	Semes	ster	Credits	%	Suggested by
0.110	Otroum	1	П	Ш	IV	Oreans	70	AICTE
1.	Foundation Courses (FC)	3	-	-	-	3	4.41	-
2.	Professional Core Courses (PCC)	9	13	3-3	(e)	22	32.35	32.35
3.	Professional Elective Courses (PEC)	6	6	6	-	18	26.47	26.47
4.	Research Methodology & IPR Courses (RMC)	3		2	_	3	4.41	2.94
5.	Employability Enhancement Courses (EEC)		2	6	14	22	32.35	38.23
	Total	21	21	12	14	68	100	100

TOTAL CREDITS: 68

Centre for Academic Courses

KPR Institute of Engineering and Technology

Coimbatore - 641 407

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Arasur. Coimbatore - 641 407



Mechanical Engineering,

APR Institute of Engineering and Technology
Arasur. Coimbatore - 641 407



P23CCP11 - Industrial Robotics	>	1	>	1	1	
P23CCP12 - MEMS and NEMS	>	Ĭ.	>	ı	I	
P23CCP13 - Computational Fluid Dynamics	>	1	>	1	1	,
P23CCP14 - Reliability in Engineering Systems	>	>	1	1	1	,
P23CCP15 - Project Management	>	1	>	>	>	,
P23CC202 - Embedded System Design	>	>	>	1	1	>
P23CCP17 - Micro and Smart Systems	>	>	>	1	1	,
P23CCP18 - Internet of things in Manufacturing	>	>	>	1	ı	,
P23CCI01 - Industrial Training / Internship	>	1	>	1	>	>

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SEMESTER I

	7,00	Ca	tego	ry: P	CC
P23CC101	COMPUTER AIDED ENGINEERING	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Enrich knowledge in fundamentals of CAE and geometric modelling
- Impart basic knowledge of machine learning
- Impart knowledge on automated production and assembly lines

UNIT I FUNDAMENTALS OF CAE

9

Introduction to CAE: CAD – CAM – FEA and CFD – CAE process – Benefits of CAE – Tools of CAE: CATIA – Solid Works – Unigraphics – Hypermesh – Ansys – Nastran – LS Dyna – EDGE cam – CAE simulations – Optimal Design techniques

UNIT II GEOMETRIC MODELLING

9

Introduction – engineering applications – Criteria for evaluating representations – Mathematical models for representing geometry – 2D simple shapes – Curves – Simple surfaces and regular shaped solids – Representing complex solids – Primitive instancing – Mesh – Sweep – Boundary – Decomposition models and CSG. Applications of geometric modelling – Estimation of volume

UNIT III MACHINE LEARNING

0

Introduction to machine learning – Examples and applications – Designing learning system – Perspectives and issues of learning system – Concept learning – Decision learning – Tree representation – Appropriate probes for decision tree – Introduction artificial neural network – Perceptions

UNIT IV AUTOMATED PRODUCTION LINES

9

Comparison of manual and automated production lines – Criteria for designing manual and automated production lines – Automated production line – System configurations – Work part transfer mechanisms – Part delivery at workstations – Applications of automated lines – Analysis of transfer lines. Automated Guided Vehicles (AGV) – Types of AGV and applications – Vehicle guidance technology – Vehicle management and safety. Conventional storage methods and equipment – Automated storage/Retrieval system and carousel storage system

UNIT V AUTOMATED ASSEMBLY SYSTEMS

9

Overview of generic material handling equipment – The 10 principles of Material handling. Conveyor systems – Types of conveyors – Operations and features – Basics of automated assembly systems – Planning for single and mixed model systems – Quantitative analysis of assembly systems with case studies. Assembly Automation – Types and configurations – Parts delivery at workstations – Product design for automated assembly – Case study

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Zeid, Ibrahim Zlid, "CAD/CAM theory and practice", 2nd edition, McGraw Hill Education, New Delhi, 2010
- 2. Groover, Michell.P. "CAD/CAM computer aided design and manufacturing", 3rd edition, Pearson,2012
- Groover, Michell.P. "Automation production systems and computer integrated manufacturing", 2nd edition, Pearson, 2015
- 4. Mitchell, Tom M. "Machine Learning", 1st edition, McGraw Hill Education, New Delhi, 2013
- 5. Alpaydin, Ethem. "Introduction to Machine Learning", 2nd edition, PHI learning, 2019

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COs	Statements	K-Level
CO1	Discuss the tools and terminologies that are associated with computer aided engineering	Understand
CO2	Discuss the various geometric modelling concepts	Understand
CO3	Explain the machine learning principles and its applications	Understand
CO4	Explain the various components of automated production lines	Understand
CO5	Explain the concepts of assembly automation	Understand

COURSE ARTICULATION MATRIX:

CO	3	1	-	1	2 8	1
CO5	3	1	-	1		1
CO4	3	1	-	1	15=16	1
CO3	3	1	: - :	1	1 1	1
CO2	3	1	=	1		1
CO1	3	1		1	1 1	1
POs	P01	PO2	PO3	PO4	PO5	P06

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER I

	* Colmu	Ca	tego	ry: P	СС
P23CC102	MECHATRONICS SYSTEM DESIGN	L	Т	Р	С
		3	0	2	4

COURSE OBJECTIVES:

- Provide fundamental knowledge on mechatronics systems
- Enhance knowledge on mechatronics system modelling and control
- Impart knowledge on practical applications of Mechatronics systems

UNIT I INTRODUCTION TO MECHATRONICS SYSTEM

9

Key elements – Mechatronics design process – Types of design – Traditional and mechatronics designs – Advanced approaches in mechatronics man machine interface – Industrial design and ergonomics – Safety

UNIT II REAL TIME INTERFACING

9

Introduction – Elements of data acquisition and control – LED display – Interfacing, Temperature Control – Stepper Motor Control – Traffic Control interface

UNIT III MECHATRONICS SYSTEM MODELLING

9

Introduction – Model categories – Model development – Simulation using software – Verification and validation – Mathematical modelling: Basic system modelling – Mechanical electrical – Fluid and thermal systems. Engineering systems: Rotational – Translational – Electro – Mechanical – Pneumatic – Mechanical – Hydro – Mechanical – Micro electro mechanical system – Dynamic responses of system: first order – Second order system – Performance measures

UNIT IV DATA ACQUISITION AND CONTROL

9

Introduction – Thermal cycle fatigue of a ceramic plate – PH control system – DC – Icing temperature control system – Skip control of a CD Player – Autofocus camera – Exposure control – Case studies in design of mechatronic products – Motion control using DC Motor and solenoids – Car engine management systems

UNIT V ADVANCED APPLICATIONS IN MECHATRONICS

9

Advanced applications of mechatronics systems: Sensors for condition monitoring – Mechatronics control in automated manufacturing – Artificial intelligence in mechatronics – Fuzzy Logic applications in mechatronics – Microsensors for mechatronics applications

LIST OF EXPERIMENTS

- 1. Control of Single & Dual Acting Cylinders using Pneumatics
- Perform AND & DR logical circuits for forward stroke of a double acting cylinder using two manual control
- 3. Cascading circuit design using PLC.
- 4. Perform the motor control operation using PLC
- Actuating multiple cylinders sequentially by cascade method
- 6. Develop electro pneumatic circuits using multiple actuators
- 7. Identify the non mental materials using sensor.
- 8. Perform the movement of 4 axis robot.

Contact Periods:

Lecture: 45 Periods

Tutorial: Periods

Practical: 30 Periods

Total:

75 Periods

Head of the Department, Mechanical Engineering.

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REFERENCES:

- 1. De Silva, "Mechatronics: A Foundation Course", Taylor & Francis, Indian Reprint, 2013
- 2. Bradley, D. Dawson, N.C. Burd and A.J. Loader, "Mechatronics: Electronics in Products and Processes", CRC Press, First Indian print, 2015
- 3. Brian morriss, "Automated manufacturing Systems Actuators Controls, sensors and Robotics", McGraw Hill International edition, 2015
- 4. Georg pelz, "Mechatronic Systems: Modeling and simulation" with HDL's, John Wiley and sons Ltd.2013
- 5. Bolton, "Mechatronics Electronic Control systems in Mechanical and Electrical Engineering" 7th edition, Pearson Education., 2016

COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level		
CO1	Define the basic concepts and elements of the mechatronics system	Understand		
CO2	Apply data acquisition system modules to interface the components of mechatronics systems	Apply		
CO3	Apply mechatronics system modelling for engineering applications			
CO4	Apply the concept of mechatronics to automate processes in the manufacturing industry	Apply		
CO5	Apply advanced tools like ANN, Fuzzy logic in mechatronics systems	Apply		

COURSE ARTICULATION MATRIX:

Correlation levels:	1: Sligh	nt (Low)	2: Moderat	e (Medium)	3: Substar	ntial (High)
СО	2	2	3	-	1	- i
CO5	2	2	3	_	1	
CO4	2	2	3	-	1	(01)
CO3	2	2	3	-	1	\$ - \$
CO2	2	1	3	-	1	1-1
CO1	2	1	3	_	1	
POs	PO1	PO2	PO3	PO4	PO5	P06

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





	* Coimba	Ca	tego	ry: P	СС	
P23CC103	COMPUTER AIDED PROCESS PLANNING	L	T	Р	С	
		3	0	0	3	

COURSE OBJECTIVES

- Understand the importance of process planning role in manufacturing
- Understand the process engineering methods
- Apply computer aided process planning in the manufacturing industry

UNIT I INTRODUCTION

9

Process planning in manufacturing cycle – Process planning and production planning – Process planning and concurrent Engineering – Group Technology (GT)

UNIT II COMPUTER AIDED POCESS PLANNING

9

Design drafting – Dimensioning – Conventional tolerance – Geometric tolerance – Input / output devices – Topology – Geometric transformation – Perspective transformation – Data structure – Geometric modelling for process planning. GT coding – The Opitz system – The MICLASS system – case studies

UNIT III PART DESIGN PRESENTATION

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9

Experience based planning – Decision table and decision trees – Process capability analysis – Process planning – Variant process planning – Generative approach – Forward and backward planning – Input format – Al

UNIT IV PROCESS ENGINEERING AND PROCESS PLANNING

0

Logical design of a process plan – Implementation considerations – Manufacturing system components – Production Volume – Number of production families – CAM – I – CAPP – MIPLAN – APPAS – AUTOPLAN and PRO – CPPP.

UNIT V INTEGRATED PROCESS PLANNING SYSTEM

9

Totally integrated process planning systems – Overview – Modulus structure – Data structure – Operation – Report generation – Expert process planning

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Leondes, Cornelius T., "Computer aided and integrated manufacturing systems." Vol. 5. World Scientific, 2003
- 2. Groover, M. P., "Automation, production systems, and computer integrated manufacturing." 4th edition, Pearson Education India,2016
- Nanua Singh, "Systems Approach to Computer Integrated Design and Manufacturing," 1st edition, John Wiley & Sons, 1996
- 4. Tien Chien Chang, Richard A.Wysk, "An Introduction to automated process planning systems," Prentice Hall,1985
- 5. Rao, "Computer Aided Manufacturing," 1st edition, Tata McGraw Hill Publishing Co., 2017



COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Discuss the process planning cycle and group technology	Understand
CO2	Develop codes for the products using OPTIZ / MICLASS system	Apply
CO3	Elaborate the principles of process engineering	Understand
CO4	Develop process planning systems using computer aided tools	Apply
CO5	Explain the concepts of integrated process planning systems	Understand

COURSE ARTICULATION MATRIX:

Correlation levels:	1: Sligh	nt (Low)		derate dium)	3: Substa	intial (High)
CO	2	_	1	_	-	
CO5	2		1	-	-	=
CO4	2	2	1	-	-	-
CO3	2	-	. 1	221	-	-
CO2	2	2	1	_	-	_
CO1	2		1	-	4	121
POs	PO1	PO2	PO3	PO4	PO5	PO6

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER I

	Comis	Ca	tego	ry: R	MC
P23RMC01	RESEARCH METHODOLOGY AND IPR	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES:

- To impart knowledge in problem formulation, analysis and solutions
- To impart skills required for technical paper writing / presentation without violating professional ethics.
- To familiarize knowledge on patent drafting and filing patents.

UNITI RESEARCH PROBLEM FORMULATION

9

Meaning of research problem – Sources of research problem – Criteria characteristics of a good research problem – Errors in selecting a research problem – Scope and objectives of research problem. Approaches of investigation of solutions for research problem – Data collection – Analysis – Interpretation – Necessary instrumentations

UNITII LITERATURE REVIEW AND DATA COLLECTION

9

Effective literature studies approaches – Analysis – Plagiarism and research ethics. Method of data collection – Types of data – Primary Data – Scales of measurement – Source and collection of data observation method – Secondary data

UNITIII TECHNICALWRITING / PRESENTATION

9

Effective technical writing: How to write report – Paper – Developing a research proposal – Format of research proposal – Presentation and assessment by a review committee

UNITIV INTRODUCTION TO INTELLECTUAL PROPERTY RIGHTS (IPR)

9

Nature of Intellectual Property: Patents – Designs – Trade and Copyright. Process of Patenting and Development – technological research – Innovation – Patenting – Development – International Scenario – International cooperation on Intellectual Property – Procedure for grants of patents – Patenting under PCT

UNITY INTELLECTUAL PROPERTYRIGHTS(IPR)

9

Patent Rights: Scope of Patent Rights – Licensing and transfer of technology – Patent information and databases – Geographical Indications – New Developments in IPR – Administration of Patent System – IPR of Biological Systems – Computer Software etc

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: -Periods

Total:

45 Periods

REFERENCES:

- Ranjit Kumar, "Research Methodology: A Step by Step Guide for beginners", 3rd edition, Sage Publications, 2010
- 2. Cooper, DR and Schindler, P S., "Business Research Methods", 9th edition, Tata McGraw Hill, 2014
- 3. Robert P.Merges, Peter S, Menell, Mark A.Lemley, "Intellectual Property in New Technological age", Volume I, Clause 8 Publishing, 2022



COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Formulate research problem	Apply
CO2	Carryout research analysis	Analyze
CO3	Develop research proposal	Evaluate
CO4	Draft process of patenting	Apply
CO5	File and publish patents in R&D	Evaluate

COURSE ARTICULATION MATRIX:

Correlation leve	els:	1: Slight (Low)	2: Moderate (Medium)	3: Substantia	l (High)
СО	_	dening - Mark	-	1	3	1
CO5	_	-		1	3	1
CO4	-		16 tm = 1	1	3	1
CO3	± c y	Nellin - Caron		1	3	1
CO2	-		-	1	3	1
CO1	_		gri -	1	3	11
POs COs	PO1	PO2	PO3	PO4	PO5	P06

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER I

		Ca	tego	ry: P	cc
P23CC104	GEOMETRIC MODELLING LABORATORY	L	Т	Р	С
		0	0 .	4	2

COURSE OBJECTIVES

- · Model 3D view of the given orthographic projections
- · Convert 3D part models to 2D drawings
- · Assemble the developed product

LIST OF EXPERIMENTS

- Feature manipulation Copy Edit Pattern Suppress History operations etc., using Solid Modeling Software
- 2. Solid modeling using Extrude Revolve Sweep etc.
- 3. Surface modeling Mesh of curves and Free form using Solid Modeling Software
- 4. Sheet metal Design creation of thin feature and manipulation
- 5. Assembly of the developed components Exploded Views Interference check Geometric dimensioning and Tolerances.
- 6. Drafting Layouts Standard & Sectional Views Detailing & Plotting
- 7. CAD data Exchange formats IGES PDES PARASOLID DXF and STL
- 8. Weldment design Design and creating the chassis of an automobile
- Casting Design create casting design with allowances positioning of runner and riser Core prints.
- 10. Design of straight helical gears and analyzing the kinematics of gear train using motion study.
- 11. Usage of standard package for designing fasteners.

Contact Periods:

Lecture: - Periods

Tutorial: -Periods

Practical: 60 Periods

Total:

60 Periods

REFERENCES:

 Radhakrishnan P, Subramanian S. and Raju V., "CAD/CAM/CIM", 2nd edition, New Age International (P) Ltd, New Delhi, 2000

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Draw 2D drawing in a CAD modelling software	Apply
CO2	Model a 3D component using solid and surface modelling techniques.	Apply
CO3		
CO4	Create weldments and casting design using modelling Software	Apply
CO5	Perform motion study on simple mechanisms.	Apply



COURSE ARTICULATION MATRIX:

Correlation levels:	1: Sligh	nt (Low)	2: Moderat	e (Medium)	3: Substar	ntial (High)
CO -	2	3	-	2	3	1
CO5	2	3	-	2	3	1
CO4	2	3	o -	2	3	1
CO3	2	3	-	2	3	1
CO2	2	3	_	2	3	1
CO1	2	3	-	2	3	1
POs	PO1	P02	PO3	P04	PO5	PO6

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER II

	* Coimba	С	atego	ory: F	CC
P23CC201	ADVANCE FINITE ELEMENT METHOD	L	Т	Р	С
		3	0	2	4

COURSE OBJECTIVES

- To impart knowledge on one- and two-dimensional finite element problems
- To study the concept of iso-parametric formulation to solve one- and two-dimensional problems.
- To learn various solution techniques to solve dynamic and non-linear problems

UNIT I ONE DIMENSIONAL PROBLEMS

9

Historical background – Basic concept of FEM – Finite element modelling – Element equations – Linear and higher order shape functions – Bar, beam, truss elements – Applications to heat transfer problems

UNIT II TWO DIMENSIONAL PROBLEMS

9

Two-dimensional heat transfer element – Application to two-dimensional heat transfer problems – Scalar variable problems in 2D – Two-dimensional fluid element – Application to two-dimensional fluid mechanics problems

UNIT III ISO-PARAMETRIC FORMULATION

9

Natural co-ordinate systems – Lagrangian interpolation polynomials – Iso parametric elements – Formulation – Shape functions one dimensional two dimensional triangular and quadrilateral elements – Serendipity element – Jacobian transformation – Numerical integration – Gauss quadrature – One, two- and three-point integration

UNIT IV DYNAMIC PROBLEMS

9

Dynamic analysis – Equations of motion – Consistent and lumped mass matrices – Free vibration analysis – Natural frequencies of longitudinal, transverse and torsional vibration – Solution of eigenvalue problems – Introduction to transient field problems

UNIT V NON-LINEAR ANALYSIS

9

Introduction to non-linear problems – Some solution techniques – Computational procedure – Material non – Linearity – Plasticity and viscoelasticity – Stress stiffening – Contact interfaces – Problems of gaps and contact – Geometric non-linearity – Modeling considerations – Free and mapped meshing – Mesh quality – Error estimate

LIST OF EXPERIMENTS

- 1. Static structural analysis of Bar, Beam and truss element
- 2. Steady state and transient analysis of rectangular plate and fins
- 3. Stress analysis of axis symmetric components
- 4. Basics of MATLAB Dealing with matrices Graphing Functions of one variable and two variables
- 5. Solve simple vibration problems using Matlab
- 6. Modal and Harmonic analysis of aircraft wing

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alter parts presign

- 7. Free and forced vibration analysis of spring mass systems.
- 8. Non-linear structural analysis of beam and rectangular plate

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Contact Periods:

Lecture: 45 Periods Tutorial: - Periods Practical: 30 Periods Total 75 Periods

Head of the Department,
Mechanical Engineering,

APR Institute of Engineering and Technology
Arasur. Coimbatore - 641 407

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REFERENCES:

- 1. Seshu.P, "Textbook of Finite Element Analysis", 2rd edition, PHI education, 2016
- Reddy. J.N., "An Introduction to the Finite Element Method", 3rd edition, McGraw Hill Education, New Delhi, 2012
- 3. Chandrupatla, Belagundu, "Introduction to Finite Elements in Engineering", 4th edition, Pearson, 2009
- Reddy, J.N., "Introduction to nonlinear finite element analysis", 1st edition, Oxford University Press,2013
- 5. Daryl L Logan, "A First Course in the Finite Element Method", 4th edition, Thomson, 2012

COURSE OUTCOMES (CO)

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Apply finite element formulations to solve one dimensional Problem	Apply
CO2	Gain knowledge in material & geometric non-linearity and plasticity	Apply
CO3	Solve the problems under dynamic conditions by applying various techniques	Apply
CO4	Formulate the finite element equation to arrive at the solutions for fluid mechanics and heat transfer problems	Apply
CO5	Interpret the finite element formulation of different production processes and its applications	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	2	-	1	1	1
CO2	3	2		1	1	1
CO3	3	2	x	1	1	1
CO4	3	2	70	1	1	1
CO5	3	2	-	1	1	1

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER II

		Ca	tego	ry: P	СС
P23CC202	ADDITIVE MANUFACTURING AND TOOLING	L	T	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Impart knowledge on fundamental and advanced technologies in additive manufacturing and its application
- Impart knowledge on the other technologies related to additive manufacturing
- Understand the applications of additive manufacturing in tooling

UNIT I INTRODUCTION

9

Need – Development of AM systems – AM process chain – Impact of AM on product development – Virtual Prototyping – Rapid Tooling – RP to AM – Classification of AM processes – Benefits – Limitations – Applications

UNIT II REVERSE ENGINEERING AND CAD MODELING

9

9

Reverse Engineering: Basics of reverse engineering – Need for reverse engineering in additive manufacturing – Methodologies for Reverse Engineering – Digitization techniques – Model reconstruction – Data processing for rapid prototyping: CAD model preparation – Data requirements – Solid modeling – Data formats – Data interfacing – Part orientation and support generation – Support structure design – Model Slicing – Tool path generation – Software for AM – Case studies

UNIT III LIQUID BASED AND SOLID BASED ADDITIVE MANUFACTURING SYSTEMS

Stereolithography Apparatus (SLA): Principle – Pre – Build process – Part – Building and post – Build processes – Photo polymerization – Part quality and process planning – Recoating issues – Materials – Advantages – Limitations and applications. Solid Ground Curing (SGC): working principle – Process – Advantages – Disadvantages and applications. Fused deposition Modeling (FDM): Principle – Details of processes – Process variables – Types – Products – Materials and applications. Laminated Object Manufacturing (LOM): Working principles – Details of processes – Products – Materials – Advantages – Limitations and applications – Case studies

UNIT IV POWDER BASED ADDITIVE MANUFACTURING SYSTEMS AND 3D- 9 PRINTING TECHNIQUES

Selective Laser Sintering (SLS): Principle – Process – Indirect and direct SLS – Powder structures – Materials – Post processing – Surface deviation and accuracy – Applications. Laser Engineered Net Shaping (LENS): Processes – Materials – Products – Advantages – Limitations and applications – Electron beam melting – Printing technologies: Binder jetting and material jetting – Processes – Materials – Advantages – Limitations and applications

UNIT V TOOLING

Classification – Soft tooling – Production tooling – Bridge tooling – Direct and indirect tooling – Fabrication processes – Applications – Case studies – Automotive – Aerospace and electronics industries

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- 1. M. Adithan, "Rapid Prototyping", 1st edition, Atlantic Publishers and Distributors Pvt. Ltd.2015
- 2. Chua, C.K., LeongK.F. and LimC.S., "Rapid prototyping: Principles and applications", World Scientific Publishers, 2010
- 3. Ian Gibson, "Additive Manufacturing Technologies", 2nd edition, Springer Nature, 2015



- 4. Liou, L.W. and Liou, F.W., "Rapid Prototyping and Engineering applications: A tool box for prototype development", 2nd edition, CRC Press,2019
- 5. J Nagendra Ms, Ganesh Prasad, P.F., "Rapid Prototyping and Allied Manufacturing Technologies", 1st edition, Airwalk Publications, 2016

COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	COs Statements	
CO1	Describe the concepts and terminology of additive manufacturing	Understand
CO2	Explain reverse engineering concepts and its importance in additive manufacturing	Apply
CO3	Explain the liquid and solid based additive manufacturing techniques	Apply
CO4	Discuss about the powder based additive manufacturing techniques with current industrial application	Apply
CO5	Explain the types of tooling in additive manufacturing	Apply

COURSE ARTICULATION MATRIX:

POs	DO4	DOG	DOS	DO4	DOE	DOC	
COs	PO1	PO2	PO3	P04	PO5	P06	
CO1	3	1	2	=		(11	
CO2	3	1	2	2-2	-	-	
CO3	3	1	2			=	
CO4	3	1	2	5 — 5		, -	
CO5	3	1	2	-	_	-	
СО	3	1	2	-	-	-	
Correlation levels:	Correlation levels: 1: Slight (Low)		2: Modera	te (Medium)	3: Substantial (High)		

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER II

		Ca	tego	ry: P	СС
P23CC203	PRODUCT LIFE CYCLE MANAGEMENT	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Know the functions and features of PLM/PDM
- Impart knowledge on product data management
- Emphasize on the different modules of PLM/PDM tools and its implementation approaches

UNIT I HISTORY, CONCEPTS AND TERMINOLOGY OF PLM

9

Introduction to PLM – Need for PLM – Opportunities of PLM – Different views of PLM – Engineering Data Management (EDM) – Product Data Management (PDM) – Collaborative Product Definition Management (PDM) – Collaborative Product Commerce (CPC) – Product Lifecycle Management (PLM). PLM/PDM Infrastructure – Network and communications – Data management – Heterogeneous data sources and applications

UNIT II PLM FUNCTIONS AND FEATURES

9

User Functions – Data vault and document management – Workflow and process management – Product structure management – Product classification and programme management. Utility Functions – communication and notification – Data transport – Data translation – Image services – System administration and application integration

UNIT III PRODUCT DATA MANAGEMENT (PDM) TECHNOLOGY

9

Product Data Management – An Introduction to concepts – Benefits and terminology – CIM Data. PDM functions – Definition and architectures of PDM systems – Product data interchange – Portal integration – PDM acquisition and implementation

UNIT IV ROLE OF PLM IN INDUSTRIES

9

Case studies on PLM selection and implementation (like auto – Aero – Electronic) – Other possible sectors – PLM visioning – PLM strategy – PLM feasibility study – Change management for PLM – Financial justification of PLM – Barriers to PLM implementation – Ten step approach to PLM – Benefits of PLM for–business – Organization – Users – Product or service – Process performance

UNIT V CUSTOMISATION/INTEGRATION OF PDM/PLM SOFTWARE

9

Applications of soft computing in product development process – Advanced database design for integrated manufacturing. PLM Customization – use of EAI technology (Middleware) – Integration with legacy database – CAD – SLM and ERP. Case studies based on top few commercial PLM/PDM tools: Sun micro systems – ABB Automation products – Siemens PLM software for Mahindra vehicles and Ford vehicles – PLM of Xerox machine – PLM for cam maintenance and repair setup

Contact Periods:

Lecture: 45 Periods

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Tutorial: - Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Ivica Crnkovic, Ulf Asklund and AnnitaPerssonDahlqvist, "Implementing and Integrating Product Data Management and Software Configuration Management", 1st edition, Artech House Publishers, 2003
- John Stark, "Global Product: Strategy, Product Lifecycle Management and the Billion Customer Question", 7th edition, Springer Publisher, 2007
- 3. John Stark, "Product Lifecycle Management: 21st century Paradigm for Product Realisation", 2nd edition, Springer Publisher, 2011



- 4. Stark, John "Product Lifecycle Management Volume1 21st century Paradigm for Product Realisation", Springer,2020
- 5. Michael Grieves, "Product Life Cycle Management", 2nd edition, Tata McGraw Hill, 2016

COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Explain history, concepts and terminology of PLM	Understand
CO2	Explain the functions and features of PLM	Understand
CO3	Discuss the features of PDM	Understand
CO4	Correlate the role of PLM in industries	Understand
CO5	Integrate PLM/PDM with other applications with case studies	Apply

COURSE ARTICULATION MATRIX:

POs						52.789
COs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	1	1	-	2
CO2	3		1	1	_	2
CO3	3	-	1	1	85 (/)	2
CO4	3	10-11-1	1	1	9 <u>11</u> 38	2
CO5	3		3	2	-	2
СО	3	_	2	2	_	2
Correlation levels:	Correlation levels: 1: Slight (Low)		2: Modera	te (Medium)	3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





SEMESTER II

		Ca	tego	ry: P	CC
P23CC204	DESIGN FOR SUSTAINABILITY	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Understand the concept of design for manufacturing, assembly and environment
- Impart knowledge on the factors influencing sustainability
- Emphasis on the role of computer application in design for manufacturing and assembly

UNIT I INTRODUCTION

9

General design principles for manufacturability – Strength and mechanical factors – Mechanisms selection – Evaluation method – Process capability – Feature tolerances – Geometric tolerances – Assembly limits – Datum features – Tolerance stacks

UNIT II FACTORS INFLUENCING FORM DESIGN

9

Working principle – Material, manufacture – design – Possible solutions – materials choice – Influence of materials on form design – Form design of welded members – Forgings and casting

UNIT III COMPONENT DESIGN AND MACHINING CONSIDERATION

9

Design features to facilitate machining – Drills – Milling cutters – Keyways – Doweling procedures – Countersunk screws – Reduction of machined area – Simplification by separation – Simplification by amalgamation – Design for machinability – Design for economy – Design for clamping – Design for accessibility – Design for assembly – Product design for manual assembly – Product design for automatic assembly – Robotic assembly

UNIT IV COMPONENT DESIGN - CASTING CONSIDERATION

9

Redesign of castings based on parting line considerations – Minimizing core requirements – Machined holes – Redesign of cast members to obviate cores. Identification of uneconomical design – Modifying the design – Group technology – Computer Applications for DFMA

UNIT V DESIGN FOR ENVIRONMENT

ç

Introduction – Environmental objectives – Global issues – Regional and local issues – Basic DFE methods – Design guidelines – Application – Life cycle assessment – Basic method – AT&T's environmentally responsible product assessment – Weighted sum assessment method – Life cycle assessment method – Techniques to reduce environmental impact – Design to minimize material usage – Design for disassembly – Design for recyclability – Design for manufacture – Design for energy efficiency – Design to regulations and standards

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Boothroyd, G, "Design for Assembly Automation and Product Design", 2nd edition, New York, Marcel Dekker, 2016
- Harry Peck, "Designing for manufacture", 4th edition, Kevin Otto and Kristin Wood, "Product Design". 1st edition, Pitman Publication, 2009
- 3. Bralla, "Design for Manufacture handbook", 2nd edition, McGraw hill. Fixel, J., "Design for the Environment", McGraw Hill,2015
- 4. Dickson, John. R, and Corroda Poly, "Engineering Design and Design for Manufacture and Structural Approach", 1st edition, Field Stone Publisher, USA,2001
- 5. Graedel T. Allen By. B, "Design for the Environment Angle", 4h edition, Wood Cliff, Prentice Hall. Reason Pub., 2005

Head of the Department, Mechanical Engineering,

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COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Outline the appropriate design principles for sustainable manufacturing	Understand
CO2	Elaborate on the factors influencing form design of a product	Understand
CO3	Design a product by considering the machining requirements	Apply
CO4	Design a component to be manufactured by casting	Apply
CO5	Design equipment considering the environmental factors	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	2	S-0	_	-	1
CO2	3	2	1 84	-	<u></u>	1
CO3	3	2		_	_	1 .
CO4	3	2	8-8	_		1
CO5	3	2	12	_	_	1
СО	3	2	N=0	_	_	1
Correlation levels:	1: Sligh	nt (Low)	2: Modera	te (Medium)	3: Substa	intial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.





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	* Coimba	С	atego	ry: P	CC
P23CC205	TECHNICAL SEMINAR	L	Т	Р	С
		0	0	4	2

COURSE OBJECTIVES

To enrich the communication skills of the student and presentations of technical topics of interest, this course is introduced. In this course, a student has to present three Technical papers or recent advances in engineering/technology that will be evaluated by a Committee constituted by the Head of the department

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

Cos	Statements	K-Level
CO1	Acquired the basic skills to for performing literature survey, paper presentation and communication	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO	-	-	-	_	3	3
Correlation levels:	1: Sligh	nt (Low)	2: Modera	te (Medium)	3: Substantial (Hig	







SEMESTER III

=		ombato!	Categ	ory: E	СС
P23CC301	PROJECT WORK PHASE - I	L	Т	Р	С
		0	0	12	6

COURSE OBJECTIVES

- To identify a specific problem for the current need of the society and collecting information related to the same through detailed review of literature
- To develop the methodology to solve the identified problem
- To prepare project reports and to face reviews and viva-voce examination

STRATEGY

The student individually works on a specific topic approved by the head of the division under the guidance of a faculty member who is familiar in this area of interest. The student can select any topic which is relevant to the area of engineering design. The topic may be theoretical or case studies. At the end of the semester – A detailed report on the work done should be submitted which contains clear definition of the identified problem – Detailed literature review related to the area of work and methodology for carrying out the work. The students will be evaluated through a viva – Voce examination by a panel of examiners including one external examiner

Contact Periods:

Lecture: 0 Periods

Tutorial: 0 Periods

Practical: 360 Periods

eriods Total:

360 Periods

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

Cos	Statements	K-Level
CO1	Identify, formulate and solve engineering problems	Apply
CO2	Carry out detailed literature review for the engineering problem	Analyze
CO3	Prepare a methodology to conduct a research	Analyze
CO4	Conduct experiments as per the methodology	Analyze
CO5	Prepare technical report and oral presentation	Apply

COURSE ARTICULATION MATRIX:

POs			ELFE-PAIR .	Nasseerian	New Assessment	450470000000000000000000000000000000000
COs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	2	2	3	3	3
CO2	3	3	3	3	3	3
CO3	2	3	3	3	3	3
CO4	2	3	3	3	3	3
CO5	3	3	2	3	3	3
СО	3	3	3	3	3	3
Correlation levels:	1: Sligh	nt (Low)	2: Moderat	e (Medium)	3: Substa	ntial (High)





		Ca	tego	ry: E	СС
P23CC401	PROJECT WORK PHASE – II	L	Т	P	С
		0	0	24	12

COURSE OBJECTIVES

- To solve the identified problem based on the formulated methodology
- To develop skills to analyze and discuss the test results, and make conclusions

STRATEGY

The student should continue the phase I work on the selected topic as per the formulated methodology under the same supervisor. At the end of the semester - after completing the work to the satisfaction of the supervisor and review committee - a detailed report should be prepared and submitted to the head of the department - The students will be evaluated based on the report submitted and the viva voce examination by a panel of examiners including one external examiner

Contact Periods:

Lecture: 0 Periods

Tutorial: 0 Periods

Practical: 360 Periods

Total: 360 Periods

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

Cos	Statements	K-Level
CO1	Identify, formulate and solve engineering problems	Apply
CO2	Develop experiment methodology for the identified engineering problem	Analyze
CO3	Conduct experiments as per the methodology	Analyze
CO4	Analyze the results and interpret the data	Evaluate
CO5	Prepare technical report, publication and oral presentation	Analyze
	, repair to a management of the property of th	

COURSE ARTICULATION MATRIX:

Correlation levels:	1: Sligh	nt (Low)	2: Modera	te (Medium)	3: Substa	antial (High)
CO	3	3	3	3	3	3
CO5	3	3	2	3	3	3
CO4	2	3	3	3	3	3
CO3	2	3	3	3	3	3
CO2	3	3	3	3	3	3
CO1	3	2	2	3	3	3
POs	PO1	PO2	PO3	PO4	PO5	PO6

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

	P23CCP01 DESIGN OF MATERIAL HANDLING SYSTEMS	Category: PEC					
P23CCP01		L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- · Familiarize the various material handling equipment's
- Enable to design various material handling equipment's
- Enable to design various drives in material handling equipment's

UNIT I MATERIALS HANDLING EQUIPMENT

9

Types of intraplant transporting facility – principal groups of material handling equipment – Choice of material handling equipment – Hoisting equipment – Screw type – Hydraulic and pneumatic conveyors – General characteristics of hoisting machines – Surface and overhead equipment – General characteristics of surface and overhead equipment and their applications. Introduction to control of hoisting equipment

UNIT II DESIGN OF HOISTS

9

Design of hoisting elements: Welded and roller chains – Hemp and wire ropes – design of ropes – pulleys – Pulley systems – Sprockets and drums – Load handling attachments. Design of forged hooks and eye hooks – Crane grabs – Lifting magnets – Grabbing attachments – Design of arresting gear – BRAKES: shoe – Band and cone types

UNIT III DRIVES OF HOISTING GEAR

9

Hand and power drives – Traveling gear – Rail traveling mechanism – Cantilever and monorail cranes – Slewing – Jib and luffing gear – Cogwheel drive – Selecting the motor ratings

UNIT IV CONVEYORS

9

Types – Description – Design and applications of belt conveyors – Apron conveyors and escalators – Pneumatic conveyors – Screw conveyors and vibratory conveyors

UNIT V ELEVATORS

9

Bucket Elevators: design – Loading and bucket arrangements – Cage elevators – Shaft way – Guides – Counter weights – Hoisting machine – Safety devices – Design of fork lift trucks

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- 1. Alexandro, M., "Materials Handling Equipments", 5th edition, MIR Publishers, 1981
- 2. Raymond A. Kulweic, "Materials Handling Handbook", 2nd edition, Wiley interscience
- Lingaiah. K. and Narayanalyengar, "Machine Design Data Hand Book", 2nd edition, McGraw Hill Education, 2017
- 4. Rudenko, N., "Materials handling equipment", 1st edition, Peace Publishers, 1970
- Siddhartha Ray, "Introduction to Materials Handling", 19th edition, New Age International Pvt. Ltd..2017



COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs					
CO1	Elaborate on the key parameters in design of material handling equipment	Understand			
CO2	Design hoist and cranes for industrial application	Apply			
CO3	Design the conveyer for transport of materials in industry	Apply			
CO4	Design conveyors for various applications	Apply			
CO5	Design the elevators for industrial applications	Apply			

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	_	_	-	-	1
CO2	3	-	_	-	_	1
CO3	3	_	-	-	-	1
CO4	3	4		-	-	1
CO5	3	-	-	-	_	1
СО	3	-	-		-	1
Correlation levels:	1: Sligh	nt (Low)				

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.



PROFESSIONAL ELECTIVE

		Ca	tego	ry: P	EC
P23CCP02	MECHANICAL BEHAVIOUR OF MATERIALS	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES:

- Study the mechanical behavior of materials under different loading and temperature conditions
- Familiarize on the various metallic and non-metallic materials
- · Select the metallic and non-metallic materials for various applications

UNIT I BASIC CONCEPTS OF MATERIAL BEHAVIOR

9

Elasticity in metals and polymers – Strengthening mechanisms – Work hardening – solid solutioning – Grain boundary strengthening – Poly phase mixture – Precipitation – Particle – Fiber and dispersion strengthening Effects of temperature – Strain and strain rate on plastic behavior – Super plasticity – Griffith's theory – Ductile – Brittle transition in steel – High temperature fracture – Creep – Larson Miller parameter – Deformation and fracture mechanism maps

UNIT II BEHAVIOR UNDER DYNAMIC LOADS AND DESIGN APPROACHES

9

Stress intensity factor and fracture toughness – Fatigue – Low and high cycle fatigue test – Crack initiation and propagation mechanisms and Paris law – Safe life – Stress life and fail-safe design approaches – Effects of surface and metallurgical parameters on fatigue – Fracture of non-metallic materials – Failure analysis – Sources of failure – Procedure for failure analysis

UNIT III SELECTION OF MATERIALS

9

Motivation for selection – Cost basis and service requirements – Selection for mechanical properties – Strength – Toughness – Fatigue and creep – Selection for surface durability corrosion and wear resistance – Relationship between material selection and processing – Case studies in material selection with relevance to areo – Auto – Marine – Machinery and nuclear applications

UNIT IV MODERN METALLIC MATERIALS

q

Dual phase steels – High strength low alloy (HSLA) steel – Transformation induced plasticity (TRIP) steel – Maraging steel – Nitrogen steel – Intermetallics – Ni and Ti aluminides – Smart materials – Shape memory alloys – Metallic glasses and Nano crystalline materials.

UNIT V BIOMATERIALS

q

Metallic implants – Stainless steel – Co – Based alloys, Tic– Based alloys – Common polymeric materials – PMMA – PGA – PCL – Bioceramics – Zirconia – Carbon – Calcium phosphates – Hydroxyapatite – Natural biomaterials – Collagen – Elastin – Cellulose – Coral – Alginate.

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total: 45 Periods

REFERENCES:

- 1. George E.Dieter, "Mechanical Metallurgy", 3rd edition, McGraw Hill Education, New Delhi, 2017
- Thomas H.Courtney, "Mechanical behavior of Materials". 3rd edition, McGraw Hill Education, New Delhi,2015
- Balasubramaniam. R, "Callister's Materials Science and Engineering", 2rd edition, Wiley India Pvt. Ltd, India,2014
- Mauil Agrawal.C, Joo L. Ong, Mark R. Appleford, and Gopinath Mani "Introduction of Biomaterials Basic Theory with Engineering Applications", 1st edition, Cambridge University Press, UK,2016
- Marc Andr'e Meyers, Krishan Kumar Chawla, "Mechanical behaviour of materials", 2rd edition, Cambridge University Press, 2009



COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level				
CO1	Explain the fundamental concepts of materials behavior	Understand				
CO2	O2 Discuss the behaviour of materials under various loads					
CO3	Select materials for different industrial applications					
CO4						
CO5	Discuss the characteristics and mechanical properties of Non- Metallic Materials	Understand				

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	P06
COs	FOI	F 02	103	1 04	100	100
CO1	3	1	122	1	_	1
CO2	3	1	1 <u>44.54</u>	1	-	1
CO3	3	1	-	1		- 1
CO4	3	1	=	1	-	1
CO5	3	1	_	1		1
СО	3	1	_	1	-	1
Correlation levels:	1: Sligh	nt (Low)	2: Modera	te (Medium)	3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.



PROFESSIONAL ELECTIVE

		Ca	tego	ry: P	EC
P23CCP03	OPTIMIZATION TECHNIQUES IN DESIGN	L	Т	Р	С
		. 3	0	0	3

COURSE OBJECTIVES

- Impart knowledge on solving problems using linear programming
- Master different optimization techniques using classical and numerical techniques
- Equip with the concepts of genetic algorithms and neural networks

UNIT I UNCONSTRAINED OPTIMIZATION TECHNIQUES

9

Introduction to optimum design – General principles of optimization – Problem formulation & their classifications – Single and multi – Variable optimization – TECHNIQUES of unconstrained minimization – Golden section – Random, pattern and gradient search methods – Interpolation methods

UNIT II CONSTRAINED OPTIMIZATION TECHNIQUE

9

Optimization with equality and inequality constraints – Direct and indirect methods using penalty functions – Lagrange multipliers – Geometric programming

UNIT III APPLICATIONS OF OPTIMIZATION TECHNIQUES

9

Structural applications – Design of simple truss members – Design applications – Design of simple, axial – Transverse loaded members for minimum cost – Weight – Design of shafts and torsionally loaded members – Design of springs.

UNIT IV OPTIMIZATION OF DYNAMIC SYSTEMS

9

Dynamic applications – Optimum design of single – Two degree of freedom systems – Vibration absorbers. Application in mechanisms – Optimum design of simple linkage mechanisms.

UNIT V GENETIC ALGORITHM AND NEURAL NETWORKS

a

GENETIC ALGORITHM (GA): Differences and similarities between conventional and evolutionary algorithms – Working principle – Reproduction – Crossover – Mutation – Termination criteria – Different reproduction and crossover operators – GA for constrained optimization – Drawbacks of GA. NEURAL NETWORKS: Organization of the brain – Biological and artificial neuron models – Characteristics of ANN – McCulloch – Pitts model – Types of neuron activation function – ANN connectivity – Learning strategies – Learning rules. Introduction to nature inspired algorithms.

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Kalyanamoy Deb, "Optimization for Engineering Design Algorithms and Examples", 2nd edition, Prentice Hall of India, 2013
- Douglas. C. Montgomery., "Response Surface Methodology: Product and Process optimization using designed experiments", 3rd edition, Wiley Blackwell,2009
- Rao, Singiresu, S., "Engineering Optimization Theory & Practice", 4th edition, John Wiley & Sons,2009
- Goldberg, D.E., "Genetic Algorithms in Search, Optimization and Machine Learning", 2nd edition, Pearson Education, 2008
- Yang, X. S., "Optimization techniques and applications with examples", 1st edition, John Wiley & Sons, 2018



COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level		
CO1	Explain in detail about single variable optimization techniques	Understand		
CO2	Apply the principle of geometric Programming in Engineering Design	Apply		
CO3	Apply Optimization techniques to design of simple mechanical elements	Apply		
CO4	Apply Optimization techniques to design of dynamic systems	Apply		
CO5	Explain the concepts of neural networks and Genetic Algorithms in optimization problems	Apply		

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	2	-	2	-	2
CO2	3	2	-	2	-	2
CO3	3	2	_	2	_	2
CO4	3	2	_	2	-	2
CO5	3	2	_	2	_	2
CO	3	2	_	2	-	2
Correlation levels:	1: Sligh	nt (Low)	2: Modera	te (Medium)	3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

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P23CCP04	QUALITY ENGINEERING	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Understand the basic principles of quality management
- Obtain knowledge on systematic procedure for maintaining records
- · Identify the causes for defects in the production system

UNIT I QUALITY ENGINEERING AND ASSURANCE SYSTEMS

9

Quality value and engineering: Definition of TQM – Approaches – Elements – Principles – Pillars – Models. Crosby's 14 steps to quality improvement. Quality Assurance systems: Definition – Objectives – Major elements – Manual – Management principles – Forms – Quality planning. FMEA – Types of FMEA – Product and process risk – Susceptibility – Occurrence and Response capability – Correction and prevention.

UNIT II LEAN MANUFACTURING SYSTEMS

9

Introduction to seven waste and their narration – Evolution of lean – Global competition – Lean Manufacturing – Value flow and Muda – Muri and Mura – Need for LM – Meeting the stakeholder's requirement – Elements of LM. Fundamental blocks of lean manufacturing – concept of 5S – Impact of 5S in lean manufacturing – Total Productive Maintenance (TPM) – Pillars of TPM – Implementation of TPM. Workflow – Small lot sizes – Pull Method – Kanban – Just in Time.

UNIT III STATISTICAL PROCESS CONTROL

9

Process capability – Old and new seven tools of quality – Control charts for variables – Control charts for attributes – Problems on control charts – Setting of product tolerances.

UNIT IV QUALITY IMPROVEMENT TECHNIQUES

9

Definition – Types – Merits – Models – Phases. Business process re-engineering – Definition – 6 R's of business process – Quality circles. Computer aided quality control.

UNIT V DESIGN OF EXPERIMENTS AND ANOVA

9

Design of experiments: Introduction – Task aids and responsibilities for DOE process steps – DOE process steps description. Analysis of variance (ANOVA): one – Way ANOVA – Two– Way ANOVA – critique of F – test – ANOVA for four level factors – Multiple level factors. Taguchi Methods – Quadratic loss function – Analysis – Robust design.8 – Point approach

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

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45 Periods

REFERENCES:

- Douglas C Montgomery, "Design and analysis of Experiments", 10th edition, John Wiley & Sons,2018
- 2. Brue G, "Six Sigma for Managers", 2nd Reprint, Tata McGraw Hill, New Delhi,2012
- De Feo J A and Barnard W W, "Six Sigma: Breakthrough and Beyond", 1st edition, Tata McGraw Hill, New Delhi, 2003
- 4. Pyzdek T and Berger R W, "Quality Engineering Handbook", 1st edition, Marcel Dekker, 1996
- 5. Dale H. Besterfield, Carol Besterfield Michna, Glen Besterfield, Mary Besterfield Sacre, "Total Quality Management", 4th edition, Pearson Education, 2015

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Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Explain the pillars of quality and practice those principles to reduce the defects that occur in the manufacturing processes	Understand
CO2	Discuss the basic concepts of lean production system	Understand
CO3	Apply statistical tools to control the quality of the products in industry	Apply
CO4	Distinguish the techniques to improve the quality of the products in an industry	Understand
CO5	Design experimental trails to conduct experiments with multiple inputs	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6	
CO1	3	1	_	-	-	. 2	
CO2	3	1	_	-	-	2	
CO3	3	2	-	_	-	2	
CO4	3	1	-	-	-	2	
CO5	3	2	-	-	-	2	
со	3	2	-	-	=	2	
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)		

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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P23CCP05		Category: PEC				
	CNC TECHNOLOGY AND PROGRAMMING	L	Т	Р	С	
		3	0	0	3	

COURSE OBJECTIVES:

- Impart knowledge on the working principle and parts of CNC machines
- Enhance knowledge on the control systems and their interface with CNC machines
- Enhance the programme skills for operating a CNC machine

UNIT I CONSTRUCTIONAL FEATURES OF CNC MACHINE TOOLS

Q

Evolution of Computerized control in manufacturing – Components – Working principle of CNC – DNC and Machining centres. Constructional features of CNC machines: Introduction – Spindle drives – Transmission belting – Axes feed drives – Slide ways – Ball screws – Torque transmission – Guideways

UNIT II ACCESSORIES AND FEEDBACK DEVICES

9

ACCESSORIES: Work tables – Spindles – Spindle heads – Beds and Columns – Tooling – Automatic Tool changer (ATC). Feedback devices: Introduction – Digital / incremental displacement measuring systems – incremental rotary encoders – Moire fringes – Feedback measurement systems and sensors – digital / absolute measuring system – Tool and work holding devices

UNIT III CONTROL SYSTEM AND INTERFACE

9

Electro – Magnetic Analogue Position Transducers: Principle – Advantages – Characteristics – Synchros – Synchro – Resolvers – Inductors – Laser interferometer. Control Systems and Interface: Open and closed loop systems – Microprocessor based CNC systems – Block diagram of typical CNC system – Description of hardware and soft interpolation systems – Standard and optional features of CNC control systems – Adaptive control

UNIT IV PART PROGRAMMING

9

Manual part programming: G - Codes and M - Codes - Programming for machining simple components - Job offset - Tool offset - Machine setting. APT language structure - APT geometry - Definition of point - Time - Vector - Circle - Plane - Patterns and matrices. APT motion commands: setup commands - Point - To point motion commands - Continuous path motion commands - Post processor commands - Control commands - Macro subroutines - Part programming preparation for typical examples

UNIT V ECONOMICS AND MAINTENANCE OF CNC MACHINE TOOLS

9

Introduction – Factors influencing selection of CNC machines – Cost of operation of CNC machines – Maintenance features of CNC machines – Preventive maintenance – Documentation – Spare parts – Training in maintenance

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- 1. Pabla, B.S. & Adithan, M. "CNC Machines", 3rd edition, New Age Publishers, 2018
- 2. Warren.S.Seames, "Computer Numerical Control: Concepts and Programming", 4th edition, Delmar Thomson Learning, 2002
- 3. James Madison, "CNC Machining Handbook", 2nd edition, Industrial Press, 2000
- 4. Peter Smid, "CNC Programming Handbook", 2nd edition, Industrial Press, 2000
- 5. Rao P.N., "CAD/CAM", 3rd edition, Tata McGraw Hill, New Delhi, 2017

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Upon completion of the course, the student will be able to

COs	Statements	K-Level		
CO1	Explain the constructional features of the CNC and its operation	Understand		
CO2	Discuss the different accessories and feedback systems in CNC machines.	Understand		
CO3	3 Discuss on the different control systems in the CNC machines			
CO4	Develop CNC part programs for simple components	Apply		
CO5	Assess costing of the machine and develop maintenance schedule for CNC machine.	Apply		

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	2	-	700).	=	(-)
CO2	3	2	-		10 TON	1 - 1
CO3	3	2	-	TT:		82-8
CO4	3	2	_	-		88-18
CO5	3	2	-	-	-	
CO	3	2	_	-		0 1
Correlation levels: 1: Slight (Low)			2: Moderat	te (Medium)	3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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P23CCP06		Category: PEC					
	SENSORS AND INSTRUMENTATION	- L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- Introduce the various sensor used in industries
- Analyze, design, build and troubleshoot variety of sensor circuits
- Explain the principles of operation of the major sensors

UNIT I REVIEW OF MEASUREMENT AND INSTRUMENTATION

9

Review of Static characteristics of Instrument systems – dynamic characteristics of Instrument systems. Review of Op – Amp circuit, passive – and active – Filters

UNIT II SIGNAL CONDITIONING

9

Analog Signal Conditioning: Principles of analog signal conditioning – Signal – Level and Bias changes. Linearization – Conversions – Filtering and impedance matching – Concept of loading. passive circuits: voltage divider – Bridge circuits – Bridge resolution – Bridge applications digital signal conditioning: review of digital electronics: digital information – Fractional binary numbers – Boolean algebra – Digital electronics circuits: comparator – Converter – Digital – To – Analog converters (dacs) – Analog – To – Digital converters (adcs): flash – Sar, dual slope

UNIT III THERMAL SENSORS

q

Definition of Temperature: thermal energy – Absolute and relative temperature – Metal resistance versus temperature devices: resistance versus temperature approximations – Resistance – Temperature Detectors (RTD) thermistors: semiconductor resistance versus temperature – Thermistor characteristics – Thermocouples: thermoelectric effects – Thermocouple characteristics – Thermocouple sensors. other thermal sensor: bimetal strips – Gas thermometers – Vapor – Pressure thermometers – Liquid – Expansion thermometers solid – State temperature sensors – Design considerations

UNIT IV MECHANICAL SENSORS

9

Displacement – Location – or Position Sensors: Resistive – Capacitive and Inductive Sensors. Variable – Reluctance Sensors – LVDT. Level Sensors. Metal Strain Gauges and Semiconductor Strain Gauges (SGs). load cells – Motion sensors: types of motion – Accelerometer principles – Types of accelerometers. pressure sensors: pressure principles – Pressure sensors (p > 1 atmosphere) – Pressure sensors (p < 1 atmosphere). flow sensors: solid – Flow – And liquid flow measurement: pipe flow principles – Restriction flow sensors, obstruction flow sensor – Magnetic flow meter

UNIT V OPTICAL SENSORS

C

Fundamentals of EM radiation. nature of EM radiation – Characteristics of light – Photometry. photodetectors: characteristics – Photoconductive detectors – Photovoltaic detectors – Photodiode detectors. photo emissive detectors. pyrometry: thermal radiation – Broadband pyrometers – Narrowband pyrometers

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Jain.R.K, "Mechanical and Industrial Measurements Process Instrumentation and Control", 11th edition, Khanna Publishers, 2003
- 2. Sawhney, A.K. "A Course in mechanical measurements and instrumentation and control", 12th edition, Dhanpat Rai,2014
- 3. Beckwith, Thomas.G, "Mechanical measurements", 5th edition, Pearson, 2004

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- 4. Sinclair, Ian, "Sensors and transducers", 1st edition, Springer, 2011
- 5. Patranabis. D, "Sensors and transducers", 2rd edition, Prentice Hall of India, 2008

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Define the basic principle of Embedded systems	Understand
CO2	Apply the principle of ARM architecture in Real time operating systems	Apply
CO3	Discuss the basic principles and architecture of PIC microcontrollers	Understand
CO4	Develop embedded system programmes for various applications	Apply
CO5	Apply the principle of IoT in embedded systems	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	=	3	(-)	(1—1)	1
CO2	2	_	3	-	-	1
CO3	2	_	3	8-8	-	1
CO4	2	_	3	-	-	1
CO5	2	<u> </u>	3	-	1-	1
СО	2	_	3	_		1
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

P23CCP07		Category: PEC					
	SUPPLY CHAIN MANAGEMENT	L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- Impart knowledge on supply chain management and its importance
- To emphasise on the supply chain control process
- Update on the recent developments in supply chain management

UNIT I BASICS OF SUPPLY CHAIN MANAGEMENT

9

Introduction – Definition of Supply Chain Management (SCM), Evolution Supply Chain Management – Key drivers of Supply Chain Management – Typology of Supply Chains – Cycle view of Supply Chain – Problems in SCM and Suggested Solutions

UNIT II PLANNING DEMAND AND SUPPLY

9

Introduction, Components of SCM – Demand Management – Demand Forecasting – Supply Management – Evolution of ERP – Concept of ERP in SCM – Quick Response and Accurate Response System in SCM – Use of other Planning Strategies

UNIT III LOGISTICS MANAGEMENT

q

Definition of Logistics and Logistics Management – Types of Logistic Activities – Importance of Logistics Management – Integrated Logistics and its Support – Determinants of Designing Logistical System – Transportation – Warehousing – Packaging

UNIT IV INVENTORY ANALYSIS AND CONTROL

9

Supply Chain Operations: Procurement Cycle – Inventory Management – Inventory Costs – Types of Inventory Models – Inventory Control Systems – Tools of Inventory Management. ABC inventory system – EOQ models for purchased parts – inventory order policies – EMQ models for manufactured parts – lot sizing techniques – inventory models under uncertainty

UNIT V RECENT TRENDS IN SUPPLY CHAIN MANAGEMENT

C

Introduction – New Developments in Supply Chain Management – Outsourcing Supply Chain Operations – Co – Maker ship – The Role of E – Commerce in Supply Chain Management – Green Supply Chain Management – Distribution Resource Planning – World Class Supply Chain Management

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Sunil Chopra, "Supply Chain Management: Strategy, Planning, and Operation", 6th edition, Pearson Education, 2016
- 2. Thomas Pyzdek Paul, A. Keller, "Six Sigma Handbook: A Complete Guide for Green Belts, Black Belts, and Managers at All Levels", 3rd edition, Tata McGraw Hill,2017
- 3. Martin Christopher, "Logistics and Supply Chain Management", 5th edition, FT Publishers, 2016
- 4. Michaell H. Hugos, "Essentials of Supply Chain Management", 3rd edition, John Wiley & Sons, 2012
- 5. Myerson, Paul, "Lean Supply Chain and Logistics Management", 3rd edition, McGraw Hill Education 2012

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Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Discuss the fundamentals of supply chain management	Understand
CO2	Explain the components of supply chain	Understand
CO3	Design systems for logistics management	Apply
CO4	Implement inventory control practices in an industry	Apply
CO5	Discuss the recent developments in six sigma	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	_	-	_	1
CO2	3	<u>ular</u>	_	_	-	1
CO3	3	_	1 4 2	_	-	1
CO4	3	_	-	-	s =	1
CO5	3	-	-	-	77	1
СО	3	_	_	== 1	_	1
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)	

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

P23CCP08		Category: PEC					
	COMPOSITE MATERIALS AND MECHANICS	L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- Know the fundamentals of composite material and its behaviour
- Have an insight on the analysis of fiber reinforced laminate design
- Familiarize on the thermos mechanical behaviour and residual stresses in laminates

UNIT I INTRODUCTION TO COMPOSITE MATERIALS

9

Definition – Matrix materials – Polymers – Metals – Ceramics – Reinforcements: Particles – Whiskers – Inorganic fibers – Metal filaments – Ceramic fibers – Fiber fabrication – Natural composite wood – Jute Mechanical properties and applications of composites – Particulate reinforced composites, dispersion – Strengthened composites – Fiber – Reinforced composites – Rule of mixtures – Characteristics of fiber – Reinforced composites

UNIT II MANUFACTURING OF COMPOSITES

9

Manufacturing of Polymer Matrix Composites (PMCs) – Hand lay – Up – Spray technique – Filament winding – Pultrusion – Resin Transfer Moulding (RTM) – Bag moulding – Injection moulding – Sandwich Mould Composites (SMC) – Manufacturing of Metal Matrix Composites (MMCs) – Solid state – Liquid state – Vapour state processing – Manufacturing of Ceramic Matrix Composites (CMCs) – Hot pressing – Reaction bonding process – Infiltration technique

UNIT III INTRODUCTION, LAMINA CONSTITUTIVE EQUATIONS

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9

Lamina Constitutive Equations: Assumptions – Macroscopic viewpoint. Generalized Hooke's Law – Definition of stress and moment resultants. Basic assumptions of laminated anisotropic plates. Laminate constitutive equations – Coupling interactions, balanced laminates – Symmetric laminates – Angle ply laminates – Cross ply laminates. Laminate structural moduli. Evaluation of lamina Properties – Quasi – Isotropic laminates

UNIT IV LAMINA STRENGTH ANALYSIS AND ANALYSIS OF LAMINATED FLAT PLATES

Introduction – Maximum stress and strain criteria. Von – Misses yield criterion for Isotropic Materials. Generalized Hill's criterion for anisotropic materials. Tsai – Hill's failure criterion for composites. Prediction of laminate failure equilibrium equations of motion. Energy formulations – Static bending analysis – Buckling analysis – Free vibrations – Natural frequencies

UNIT V TESTING OF COMPOSITES

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Mechanical testing of composites, tensile testing – Compressive testing – Flexural testing – Impact testing – Micro Vickers hardness testing – Inter – Laminar shear testing – Fatigue testing – Moisture absorption testing – Biodegradability testing – And Morphological analysis of composite laminates

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- 1. Autar K. Kaw., "Mechanics of Composite Materials", 2nd edition, Taylor & Francis, 2006
- Agarwal, B.D., and Broutman L.J., "Analysis and Performance of Fiber Composites", 3rd edition, John Wiley & Sons, 2015
- Chung, Deborah D.L., "Composite Materials: Science and Applications", 1st reprint, Ane Books Pvt Ltd, Springer, 2009
- Madhujit Mukhop, "Mechanics of FRP Composite Materials & Structure", 2nd edition, Universities Press,2022

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 Hyer, M.W., "Stress Analysis of Fiber Reinforced Composite Materials", 5th edition, McGraw Hill,2009

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Explain the fundamentals of composite materials	Understand
CO2	Discuss the manufacturing processes of composite materials.	Understand
СОЗ	Discuss the equation that governs the mechanics of composites	Apply
CO4	Evaluate the strength of the laminates	Apply
CO5	Make use of equipment's to measure the properties of composites	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	P06
COs	3					1
CO1	3	_		=		3.
CO2	3	-	-	-	0-2	1
CO3	3	-	-	- 1	(())	1
CO4	3	-	-	_	s - 3	1
CO5	3	-	_	-	7 — 3	1
со	3	_	_	_	-	1
Correlation levels:	1: Slight (Low)		2: Modera	te (Medium)	3: Substa	ntial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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P23CCP09	DESIGN FOR MANUFACTURING SYSTEMS	L T P	С		
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COURSE OBJECTIVES

- Emphasise on the processes followed in industries
- Highlight the improvement in quality by implementing the industrial processes
- To impart knowledge on the manufacturing processes and control

UNIT I LEAN MANUFACTURING AND VALUE STREAM MAPPING

9

Evolution of Mass production – Traditional vs. Mass production – Evolution of Toyota (Lean) Production System – Business Dynamics of Lean production – Principles of Lean production: Value, Value stream – Flow – Pull – Perfection. Need for Value Stream mapping – Steps involved in Value stream mapping – Choose value stream – PQ and PR analysis – Current State map – Lean Metrics – Future State Map – Kaizen plans

UNIT II FLEXIBLE MANUFACTURING SYSTEMS

9

Group Technology: Introduction – objectives – part families – algorithms and models for G.T. – Rank order clustering – Bond energy – Mathematical model for machine – component cell formation. Introduction to FMS – Concepts – Advantages – Components of FMS and their integration in the data processing systems – FMS scheduling – Examples of FMS installations. Distributed data processing in FMS

UNIT III ENTERPRISE RESOURCE PLANNING

9

Role of Enterprise Resource Planning (ERP) in manufacturing – Materials Requirement Planning (MRP) – Master Production Schedule (MPS) – Bill of Material (BOM) – Inventory Records – Closed Loop MRP – Manufacturing Resource Planning (MRP–II) – Manufacturing and Production Planning Module of an ERP System – Distribution Requirements Planning (DRP) – Product Data Management (PDM) – Data Management – Process Management – Functions of PDM – Benefits of PDM – Manufacturing Operations – Make – To – Order (MTO) and Make – To – Stock (MTS) – Assemble – To – Order (ATO) – Engineer – To – Order (ETO) – Configure – To – Order (CTO)

UNIT IV MANUFACTURING SYSTEMS & CONTROL

9

Automated Manufacturing Systems – Modelling – Role of performance modelling – Simulation models Analytical models. Product cycle – Manufacturing automation – Economics of scale and scope – Input/output model – Plant configurations. Performance measures – Manufacturing lead – Time – Work in process – Machine utilization – Throughput – Capacity – Flexibility – performability – Quality. Control Systems – Control system architecture – Factory communications – Local area networks – Factory networks – Open systems interconnection model – Network to network interconnections – Manufacturing automation protocol – Database management system.

UNIT V BENCHMARKING AND SIX SIGMA

9

Introduction – Understanding the Benchmarking Concept – Benchmarking Process – Benchmarking Procedure equipment – Additional control. Concept of six sigma – Steps involved in implementing six sigma – Advantages of six sigma.

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Panneerselvam R., "Production and Operations Management", 3rd edition, Prentice Hall of India Pvt, Ltd., New Delhi, 2012
- Mike Rother and Rother Shook, "Learning to See: Value Stream Mapping to Create Value and Eliminate Muda", 3rd edition, The Lean Enterprise Institute, 2006

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- James Womack and Daniel T. Jones, "Lean Thinking: Banish Waste and Create Wealth in Your Organization", 2nd edition, Free Press,2003
- James D Dilworth, "Production and Operations Management", 2nd edition, Tata McGraw Hill, New Delhi.2003
- 5. Pascal Dennis, "Lean Production Simplified: A plain Language Guide to the World's Most Powerful Production System", 3rd edition, Productivity Press,2015

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Explain the importance of lean manufacturing and value stream mapping	
CO2	Implement the concept of Flexible Manufacturing Systems in industrial process	
CO3	Apply the concept of ERP in an industry	Apply
CO4	Ensure the quality of a product by adopting appropriate manufacturing	
CO5	Explain on the tools and procedures in implementing six sigma concepts	Apply

COURSE ARTICULATION MATRIX:

gurer production (1) (1) (2) (3)

POs	PO1	PO2	PO3	PO4	PO5	P06
CO1	3	-	2	1 100	5 9 -1	2
CO2	3	-	2	-	-	2
CO3	3	-	2	-	: - : X	2
CO4	3	-	2		-	2
CO5	3	-	. 2	-	-	2
СО	3	_	2	_		2
Correlation levels:	1: Slight (Low)		2: Modera	te (Medium)	3: Substa	ntial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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P23CCP10

PERFORMANCE MODELLING AND ANALYSIS OF MANUFACTURING SYSTEMS

Category: PEC						
L	Т	Р	С			
3	0	0	3			

COURSE OBJECTIVES

- Instigate the importance of analyzing a manufacturing system
- Familiarize with the concepts involved in modeling a manufacturing system
- Emphasis the networking strategies in a manufacturing system

UNIT I MANUFACTURING SYSTEMS AND CONTROL

Automated Manufacturing Systems - Modeling - Role of performance modeling - Simulation models Analytical models. Product cycle - Manufacturing automation - Economics of scale and scope -Input/output model - Plant configurations. Performance measures - Manufacturing lead - Time - Work in process - Machine utilization - Throughput - Capacity - Flexibility - Performability - Quality Control systems - Control system architecture - Factory communications - Local area network interconnections - Manufacturing automation protocol - Database management system

MANUFACTURING PROCESSES UNIT II

Poisson process - Discrete Time Markov (DTM) chain models - Definition and notation - Sojourn times in states - Examples of DTMCs in manufacturing - Chapman - Kolmogorov equation - Steady - State analysis. Continuous Time Markov Chain Models - definitions and notation - Sojourn times in states examples of CTMCs in manufacturing - Equations for CTMC evolution - Markov model of a transfer line. Birth and Death Processes in Manufacturing - Steady state analysis of BD Processes - Typical BD processes in manufacturing.

UNIT III QUEUING MODEL

Notation for queues - Examples of queues in manufacturing systems - Performance measures -Little's result – Steady state analysis of M/M/m queue – queues with general distributions – And queues with breakdowns - Analysis of a flexible machine centre

UNIT IV **QUEUING NETWORKS**

Éxamples of QN models in manufacturing - Little's law in queuing networks - Tandem queue - An open queuing network with feedback - An open central server model for FMS - Closed transfer line -Closed server model - Garden Newell networks

UNIT V PETRINETS

47

Classical Petri Nets - Definitions - Transition firing and reachability - Representational power -Properties - Manufacturing models. Stochastic Petri Nets - Exponential timed Petri Nets - Generalized Stochastic Petri Nets - Modeling of KANBAN systems - Manufacturing models

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total: 45 Periods

REFERENCES:

- 1. Viswanadham, N and Narahari, Y. "Performance Modelling of Automated Manufacturing Systems", 3rd edition, Prentice Hall of India, New Delhi, 2003
- 2. Trivedi, K.S. "Probability and Statistics with Reliability, Queuing and Computer Science Applications", 2nd edition, John Wiley & Sons, 2008
- 3. Mikell P. Groover, "Automation, Production Systems, and Computer Integrated Manufacturing", 4th edition, Pearson Education, 2014
- 4. Mor Harchol, Balter, "Performance Modeling and Design of Computer Systems: Queueing Theory in Action", 1st edition, Cambridge University, 2013

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5. Alasdair Gilchrist., "Industry 4.0: The Industrial Internet of Things", 1st edition, Apress,2017

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Explain the importance of performance control of a manufacturing system	Understan
CO2	Explain the methodologies to simplify the manufacturing processes	Understan
CO3	Apply the queuing models in manufacturing processes	Apply
CO4	Apply the queuing networks in manufacturing processes	Apply
CO5	Apply Petrinetsin manufacturing processes	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	2	2	_	-	_	2
CO2	2	2	10-20	_		2
CO3	3	2	_	_	_	2
CO4	3	2		-	-	2
CO5	3	2	-	-		2
СО	3	2	_	_	==	2
Correlation levels:	1: Slight (Low)		2: Moderat	te (Medium)	3: Substa	antial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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		Category: PEC				
P23CCP11	INDUSTRIAL ROBOTICS	L	Т	Р	С	
		3	0	0	3	

COURSE OBJECTIVES

- · Impart knowledge on fundamentals of robotics
- Make the student to learn on robotic motions
- Familiarize with the actuators and sensors used in robots

UNIT I FUNDAMENTAL OF ROBOTICS

9

Introduction – Definition of robot – Classification of robots – History of robotics – Robot components – Degree of freedom – Robot joints – Robot coordinates – Reference frames – Programming modes – Robot characteristics – Robot work space – Robot languages – Advantages and disadvantages of robots – Robot as a mechanisms – Matrix representation – Representation of a point in a space – Representation of a vector in space – Representation of a frame in a reference frame – Representation of rigid body

UNIT II ROBOT KINEMATICS

9

Homogeneous transformation matrices – Representation of a pure translation – Pure rotation about an axis – Representation of combined transformations – Transformations relative to the rotating – Inverse of transformation matrices – Forward and inverse kinematics of robots – Forward and inverse kinematic equations for position and orientation

UNIT III DIFFERENTIAL MOTIONS AND VELOCITIES

9

Introduction – Differential relationship – Jacobian differential motions of a frame – Translations, rotation – Rotating about a general axis – Differential transformation of a frame – Differential changes between frames – Calculation of jacobian – Relation between jacobian and the differential operator – Inverse jacobian, basics of trajectory planning – Path Vs trajectory – Joint space trajectory planning – Third order polynomial trajectory planning

UNIT IV ROBOT DYNAMICS AND APPLICATION

9

Lead through programming – Robot programming as a path in space – Motion interpolation Wait – Signal and Delay – Branching capabilities and limitations – Robot Languages Textual robot languages – Generations – Robot language structures – Elements in functions – Applications – Material transfer – Machine loading / unloading – Processing operations – Assembly and inspections

UNIT V ARTIFICIAL INTELLIGENCE FOR ROBOT

9

Introduction to Al – State space search – Generate and test – Simple search – Depth First Search (DFS) – Breadth First Search (BFS) – Comparison of DFS and BFS – Quality solutions – Heuistic search – Heuristic functions – Best first search – Hill climbing – Local maxima – Solution space search

Contact Periods:

Lecture: 45 Periods

Tutorial: - Periods

Practical: - Periods

Total: 45 P

45 Periods

REFERENCES:

- 1. R.K.Mittal and I.J.Nagrath, "Robotics and Control", 4th reprint, Tata McGraw Hill, 2011
- 2. JohnJ.Craig, "Introduction to Robotics Mechanics and Control", 3rd edition, Pearson Education, 2009
- R.D.Klafter, T.A.Chimielewski and M.Negin, "Robotic Engineering, An Integrated Approach", 3rd edition, Prentice Hall of India, New Delhi, 2014
- B.K.Ghosh, "Control in Robotics and Automation: Sensor Based Integration", 2nd edition, Allied Publishers, 2015
- 5. Deepak Khemain, "A first course in Artificial Intelligence", 6th edition, Tata McGraw Hill, 2017

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Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Summarize the fundamentals of industrial robots	Understand
CO2	Execute the kinematic motions of robot for some specific	Apply
CO3	Carry out the motion and velocity studies on some specific	Apply
CO4	Implement the dynamic motions of robot for some specific	Apply
CO5	Summarize the basic concepts of artificial intelligence for robot	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	-	3	-		_
CO2	3	-	3	-	_	<i>i</i> −. 1
CO3	3	-	3	-	, , , , , , , , , , , , , , , , , , , 	-
CO4	3	_	3	-	-	-
CO5	3	-	3	- 1		-
СО	3	_	3	-	_	-
Correlation 1: Slight (Low)			2: Modera	te (Medium)	3: Substa	ntial (High)

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

		Ca	tego	ry: P	EC
P23CCP12	MEMS AND NEMS	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES

- Familiarize with the basic concepts of MEMS and NEMS
- Impart knowledge on the MEMS manufacturing process
- Impart knowledge on micro sensors and micro actuators involved in MEMS and NEMS

UNIT I OVERVIEW AND INTRODUCTION

9

New trends in Engineering and Science: Micro and nano scale systems – Introduction to design of MEMS and NEMS – Overview of nano and micro electromechanical Systems – Applications of Micro and nano electro mechanical systems – Micro electromechanical systems – Devices and structures definitions – Materials for MEMS: silicon – Silicon compounds – polymers – Metals

UNIT II MEMS FABRICATION TECHNOLOGY

9

Microsystem fabrication processes: photolithography — Ion implantation — Diffusion — Oxidation. thin film depositions: LPCVD — Sputtering — Evaporation — Electroplating — Etching techniques — Dry and wet Etching — Electrochemical etching — Micromachining — Bulk micromachining — Surface micromachining — High aspect — Ratio (LIGA and LIGA — like) technology — Packaging — Microsystems packaging — Essential packaging technologies — Selection of packaging materials

UNIT III MICRO SENSORS

9

MEMS Sensors: design of acoustic wave sensors – Resonant sensor – Vibratory gyroscope – Capacitive and piezoresistive pressure sensors – Engineering mechanics behind these microsensors – Case study: piezo – Resistive pressure sensor

UNIT IV MICRO ACTUATORS

9

Design of Actuators: actuation using thermal forces – Actuation using shape memory alloys – Actuation using piezoelectric crystals – Actuation using electrostatic forces (parallel plate – Torsion bar – Comb drive actuators) – Micromechanical motors and pumps. case study: comb drive actuators

UNIT V NANO SYSTEMS AND QUANTUM MECHANICS

9

Atomic structures and quantum mechanics – Molecular and nanostructure dynamics: shrodinger equation and wave function theory, density functional theory – Nanostructures and molecular dynamics, electromagnetic fields and their quantization – Molecular wires and molecular circuits

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Tai Ran Hsu," MEMS and Microsystems Design and Manufacture", 3rd edition, McGraw Hill Education, 2002
- 2. Chang Liu, "Foundations of MEMS", 1st edition, Pearson education India limited, 2006
- 3. Mahalik, Nitaigour Premchand, "MEMS", 2nd edition, McGraw Hill Education, 2007
- Rai Choudhury. P, "MEMS and MOEMS technology and application", 2nd edition, PHI Learning, 2011
- 5. Adams, Thomas.M, "Introductory MEMS: fabrication and applications" 1st edition, Springer, 2014

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Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Summarize the fundamentals of MEMS and NEMS	Understand
CO2	Discuss the fabrication processes in MEMS and NEMS	Understand
CO3	Select appropriate sensors for MEMS and NEMS	Understand
CO4	Select appropriate actuators for MEMS and NEMS	Understand
CO5	Explain the mechanics involved in MEMS and NEMS	Understand

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6	
CO1	2	-	3	-		1	
CO2	2	_	3	_	-	1	
CO3	2	-	3	-	-	1	
CO4	2	9-8	3	-	-	1	
CO5	2	; —)	3 — 3	- 3 -	-		1
СО	2	9 — 5	3		_	1	
Correlation levels:	1: Slig	1: Slight (Low)		te (Medium)	3: Substa	ntial (High)	

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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		Category: PEC					
P23CCP13	COMPUTATIONAL FLUID DYNAMICS	L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- · Introduce numerical modeling and its role in the field of heat-fluid flow and combustion
- Enable the students to understand the various discretization methods
- Solve complex problems in the field of heat transfer and fluid dynamics

UNIT I GOVERNING DIFFERENTIAL EQUATIONS AND DISCRETISATION TECHNIQUES

Basics of Heat Transfer – Fluid flow – Mathematical description of fluid flow and heat transfer Conservation of mass – Momentum – Energy and chemical species – Classification of partial differential equations – Initial and Boundary Conditions – Discretization techniques using finite difference methods – Taylor's Series – Uniform and non – Uniform Grids – Numerical Errors – Grid Independence Test

UNIT II DIFFUSION PROCESSES: FINITE VOLUME METHOD

Steady one – Dimensional diffusion – Two – And three – Dimensional steady state diffusion problems – Discretization of unsteady diffusion problems – Explicit – Implicit and Crank – Nicholson's schemes – Stability of schemes

UNIT III CONVECTION -DIFFUSION PROCESSES: FINITE VOLUME METHOD

One dimensional convection – Diffusion problem – Central difference scheme – Upwind scheme Hybrid and power law discretization techniques – QUICK scheme

UNIT IV FLOW PROCESSES: FINITE VOLUME METHOD

Discretization of incompressible flow equations – Pressure based algorithms – SIMPLE – SIMPLER & PISO algorithms

UNIT V MODELING OF COMBUSTION AND TURBULENCE

Mechanisms of combustion and Chemical Kinetics – Overall reactions and intermediate reactions – Reaction rate – Governing equations for combusting flows. Simple Chemical Reacting System (SCRS) – Turbulence – Algebraic Models – One equation model – k – ω models – Standard and High and Low Reynolds number models

Contact Periods:

Lecture: 45 Periods Tutorial: -Periods Practical: - Periods Total: 45 Periods

REFERENCES:

- 1. John D. Anderson. JR. "Computational Fluid Dynamics the Basics with Applications" 2nd edition, Tata McGraw Hill Education, 2017
- Versteeg and Malalasekera, N, "An Introduction to Computational Fluid Dynamics the Finite Volume Method," 2nd edition, Pearson Education, 2014
- Ghoshdastidar, P.S., "Computer Simulation of flow and heat transfer", 2nd edition, McGraw Hill Education, 2006
- 4. Jiyuan Tu, Guan Heng Yeoh, Chaogun Liu, "Computational Fluid Dynamics A Practical Approach", 2nd edition, Butterworth Heinemann An Imprint of Elsevier, Madison, 2012
- 5. Suhas V. Patankar, "Numerical heat transfer fluid flow", 1st edition CRC Press,2017

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Upon completion of the course, students will be able to

COs	Os Statements				
CO1	Derive the governing equations and boundary conditions for Fluid dynamics	Understand			
CO2	Analyze Finite difference and Finite volume methods for Diffusion	Apply			
CO3	Analyze Finite volume method for Convective diffusion	Apply			
CO4	Analyze Flow field problems based on Pressure based algorithms, SIMPLE, SIMPLER &PISO algorithms	Apply			
CO5	Solve the Turbulence models and simple chemical reacting system	Apply			

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
CO1	3	_	2	-	-	1
CO2	3	-	2	-	-	1
CO3	3	_	2	_	-	1
CO4	3	-	2	-	-	1
CO5	3	824	2	_	-	. 1
CO	3	_	2	-	-	1
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)	

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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23CCP14		Category: PEC					
	RELIABILITY IN ENGINEERING SYSTEMS	L	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- · Impart knowledge on the reliability tools and its features
- Emphasise on the reliability testing methods
- Arrive at optimum solutions to improve reliability

UNIT I BASIC PROBABILITY AND RELIABILITYTHEORY

9

Elements of probability – Probability distributions – Random variables – Density and Distribution functions – Expected value and standard deviation – Binomial distribution – Poisson distribution – Normal distribution – Exponential distribution – Weibull distribution. Definition of Reliability: Definition of terms used in reliability – Component reliability – Hazard rate – Derivation of the reliability function in terms of the hazard rate

UNIT II NETWORK MODELING AND RELIABILITY EVALUATION

9

Evaluation of network Reliability / Unreliability – Series systems – Parallel systems – Series – Parallel systems – Partially redundant systems – Types of redundancies – Evaluation of network Reliability / Unreliability using conditional probability method – Paths based and Cutest based approach – Complete event tree and reduced event tree methods – Examples

UNIT III TIME DEPENDENT PROBABILITY

9

Reliability functions f(t) - F(t) - R(t) - h(t) - Relationship between these functions - Baths tubs curve - Exponential failure density and distribution functions - Expected value and standard deviation of Exponential distribution - Measures of reliability - MTTF- MTTR- MTBF - Evaluation of network reliability / Unreliability of simple Series- Parallel - Series-Parallel systems - Partially redundant systems - Examples

UNIT IV RELIABILITY LIFE TESTING METHODS

9

Reliability Life Testing – Test time calculations – Burn–in testing – Acceptance testing – accelerated life testing and Experimental Design – Reliability Growth Testing – Growth process – Idealized growth curve and other growth models. Goodness of Fit tests – Chi – Square goodness of fit test – Bartlett's test for the exponential distribution – Mann's test for the weibull distribution – Kolmogorov smirnov test for normal and lognormal distributions and tests for the power law process model

UNIT V MACHINE LEARNING FOR RELIABILITY

9

Basic machine – Learning modelling – Classification: predicting in to buckets – Regression: predicting numerical values – Model generalization: assessing predictive accuracy for new data – Evaluation of classification models – Regression models – Model optimization through parameter tuning

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- G. Haribaskaran, "Probability, Queuing Theory & Reliability Engineering", 2nd edition, Laxmi publications, 2006
- Mohit S.Moheshworkar, Pallavi. Moheshworkar," Text book of Reliability and Maintenance Engineering", 14th edition, SK Kataria & Sons, New Delhi, 2014
- Patrick D.T. O'Connor, Andre Kleyner, "Practical Reliability Engineering", 5th edition, John Wiley & Sons. 2005
- 4. Birolini, Alessandro., "Reliability Engineering: Theory and Practice", 8th edition, Springer, 2017

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 Henrik brink, Richards W.Joseph, Mark Fetherolf, "Real World Machine Learning", 1st edition, Manning Publication, 2016

COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Explain the fundamental probability and reliability concepts	Understand
CO2	Evaluate reliability by network modeling	Apply
CO3	Conduct failure analysis by various techniques	Apply
CO4	Perform various life testing methods for reliability measurement	Apply
CO5	Optimize the Reliability of a system using machine learning	Apply

COURSE ARTICULATION MATRIX:

		r										
POs	PO1	PO2	PO3	PO4	PO5	PO6						
CO1	3	2	_	-		2						
CO2	3	2	-	-	-	2						
CO3	3	2		-	<u> </u>	2						
CO4	3	2	_	-	-	2						
CO5	CO5 3 2	2	2	2	2	2	2	2	_	-	_ 2	
СО	3	2	_		-	2						
Correlation levels:	1: Sligl	nt (Low)	2: Modera	te (Medium)	3: Substa	antial (High)						

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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P23CCP15		Category: PEC					
	PROJECT MANAGEMENT	L T P		Р	С		
*		3	0	0	3		

COURSE OBJECTIVES

- Inculcate knowledge on the basics of project management
- Explore the criteria and processes for project management
- Make aware of the project management standards

UNIT I INTRODUCTION TO PROJECT MANAGEMENT

9

Definition of project purpose – Scope – Time – Quality and organization structure. Basic and detailed engineering: Degree of automation – Project S curves – Manpower considerations – Inter – Department and inter – Organization interactions – Multi agency interaction. Types of projects and types of contracts e.g. – EPC – BOOT etc

UNIT II PROJECT COST ESTIMATION

9

Types and estimates – Pricing process – Salary and other overheads – Man – Hours – Materials and support costs. program evaluation and review techniques (PERT) and critical path method (CPM) – Estimating activity time and total program time – Total PERT/CPM planning crash times – Software 's used in project management

UNIT III ENGINEERING DESIGN CRITERIA

9

Project engineering documents and drawing: Process flow sheets – Mechanical flow sheets – Instrument index sheets – Loop wiring diagram – Panel drawings and specifications – Plot plans – Installation details – Special drawings – Purchase requisition – Other documents. Pneumatic versus electronics system Transmission systems: Pneumatic & Electronic – Materials – Distribution – Terminations and Identification

UNIT IV MAINTENANCE AND SERVICE

9

Organizing: Documents – Schedule – Cost control Ordering and Receiving equipment and Material: Purchase orders – Material status – Storage Installing instrument systems: Procedures – Coordination – Good installation practices. Startup: Placing instruments in service – Tuning loop controls – Evaluating process upsets and disturbances – Repairing or replacing defective equipment – Special equipment – Additional control

UNIT V PROJECT MANAGEMENT SOFTWARE

q

Introduction – Software tools such as Microsoft Project – Primavera Project Planner – Crystal Ball and Pro Chain – Advantages of using Project Management Software – Common Features in the Project Management Software – Illustration – Case studies

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Harlod Kerzner and Van Nostrand "Project management: A systems approach to planning scheduling and controlling", 11th edition, John Wiley & Sons, 2013
- 2. W.G. Andrew and H.B. Williams "Applied Instrumentation in Process Industries", 3rd edition, Gulf Professional Publishing,2008
- Michael D. Whitt, "Successful Instrumentation & Control Systems Design", 2nd edition, International Society of Automation, 2015
- 4. Tapan B. Bagchi, "Concepts, Methods & Implementation", 2nd edition, Wheeler Publication, 2003
- 5. Bela G Liptak, "Instrument Engineers Handbook: Process Control", 3rd edition, CRC Press,2013

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COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Solve an electric network by applying basic laws and reduction methods	Apply
CO2	Apply the concept of network theorems for electric circuits	Apply
CO3	Explain the concepts of three phase circuits and its power measurement	Understand
CO4	Analyze the transient response of electric circuits and to infer two port network parameters	Analyze
CO5	Interpret the resonance phenomenon and coupled circuits	Apply

COURSE ARTICULATION MATRIX:

POs	PO1	PO2	PO3	PO4	PO5	PO6
COs CO1	3	_	1	2	2	1 :
CO2	3	-	1	2	2	1
CO3	3	7-	1	2	2	1
CO4	3	==0	1	2	2	1
CO5	3	8=3	1	2	2	1
CO	3	-	1	2	2	1
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)	

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

P23CCP16		Category: PEC					
	EMBEDDED SYSTEM DESIGN	L T	Т	Р	С		
		3	0	0	3		

COURSE OBJECTIVES

- Provide an overview of embedded system design principles
- Understand the concepts of real time operating systems
- Provide exposure to embedded system development tools using basic programming techniques

UNIT I INTRODUCTION TO EMBEDDED SYSTEMS

9

Overview of embedded systems – Embedded system design process – Challenges – Common design metrics and optimization. Hardware – Software design – Embedded product development

UNIT II REAL TIME OPERATING SYSTEM

9

Real time operating systems architecture – Tasks and task states – Tasks and data – Semaphore and shared data – Message queues – Mail boxes and pipes – Encapsulating semaphores and queues – Interrupt routines in an RTOS Environment. Introduction to Vx works, RTLinux

UNIT III PIC MICROCONTROLLERS

9

Programmable Interrupt Controller (PIC) Architecture – Instruction set – Addressing modes – Timers – Interrupt logic – CCP modules – Analog to digital convertor (ADC)

UNIT IV EMBEDDED PROGRAMMING

•

I/O Programming - Interrupts and timer application - Interfacing keypad - Interfacing LCD - Interfacing ADC/DAC

UNIT V IOT REFERENCE ARCHITECTURE

9

Industrial Automation – Service oriented architecture-based device integration – SOCRADES: realizing the enterprise integrated Web of Things – IMC–AESOP: from the Web of Things to the Cloud of Things

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Project

- Periods

Total:

45 Periods

REFERENCES:

- Steve Heath, "Embedded Systems Design", 2nd edition, Newness publications, 2009
- 2. Tammy Noergaard, "Embedded Systems Architecture: A Comprehensive Guide for Engineers and Programmers", 2nd edition, Butterworth Heinemann Ltd,2013
- 3. David E. Simon, "An embedded software primer", 1st edition, Pearson Education, 2002
- 4. Rajkamal, "Microcontrollers Architecture Programming Interfacing and System Design", 2nd edition, Pearson Education, 2011
- Rajkamal, "Embedded Systems Architecture Programming and Design", 2nd edition, Tata McGraw Hill, 2016

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COURSE OUTCOMES:

Upon completion of the course, the student will be able to

COs	Statements	K-Level
CO1	Define the basic principle of Embedded systems	Understand
CO2	Discuss the basic concepts of lean production system	Apply
CO3	Apply statistical tools to control the quality of the products in industry	Understand
CO4	Distinguish the techniques to improve the quality of the products in an industry	Analyze
CO5	Design experimental trails to conduct experiments with multiple inputs	Apply

COURSE ARTICULATION MATRIX:

POs	DO1	DO3	DO3	DO4	DOS	DOG
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COURSE OUTCOMES (CO)

Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	Discuss about smart materials and Microsystems	Understand
CO2	Explain the various sensors and actuators for microsystems	Understand
СОЗ	Explain the various micro machining processes	Understand
CO4	Create microsystems solid models	Apply
CO5	Integrating of microsystems with microelectronics	Apply

COURSE ARTICULATION MATRIX:

Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)	
СО	1	1	3	1	_	1
CO5	1	1	3	1	-	1
CO4	1	1	3	11	-	1
CO3	1	1	3	1	<u>—</u>	1
CO2	1	1	3	1	-	1
CO1	1	1	3	1		- 1
POs	PO1	PO2	PO3	PO4	PO5	PO6

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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PROFESSIONAL ELECTIVE

P23CCP18		Ca	tego	ry: P	EC
	INTERNET OF THINGS IN MANUFACTURING	L	Т	Р	С
		3	0	0	3

COURSE OBJECTIVES:

- Study the basics of IoT cloud computing– smart manufacturing
- Familiarize on the various internet protocols for manufacturing system
- Impart knowledge on communication and information system in manufacturing

UNIT I IOT AND CLOUD COMPUTING

9

Introduction – Physical design of IoT – Logical design of IoT – IoT enabling technologies – Domain specific IoTs – IoT design methodology – Logical design – Iot physical devices (such as Raspberry Pi – Pcduino – Beaglebone black – Cubieboard) – Introduction to cloud computing: cloud models – Cloud service examples – Cloud based services & applications – Cloud service and platforms

UNIT II UNDERSTANDING INTERNET PROTOCOLS

5

Simplified osi model – Network topologies – Standards – Types of internet networking – Ethernet – WiFi – Local networking – Bluetooth – Bluetooth low energy (BLE) – Zigbee – 6LoWPAN – Sub 1 GHz–RFID – NFC – Proprietary protocols – Simplicity – Networking design – Push – Pull and polling – Network api

UNIT III APPLIED MACHINE TO MACHINE COMMUNICATION

9

Introduction to M2M - Description of M2M market - Segments / applications - Automotive - Smart telemetry - Surveillance and security - M2M industrial automation - M2M terminals and modules

UNIT IV INFORMATION SYSTEMS IN MANUFACTURING

9

Manufacturing organizations – Management – And the networked enterprises – Globalization challenges and opportunities – Dimensions of information systems – Approaches to study information system – Technical and behavioral approach – Information technology infrastructure

UNIT V INTRODUCTION TO SMART MANUFACTURING

9

Smart applications online predictive modeling – Monitoring and intelligent control of machining / manufacturing and logistics/supply chain processes – Smart energy management of manufacturing processes and facilities

Contact Periods:

Lecture: 45 Periods

Tutorial: -Periods

Practical: - Periods

Total:

45 Periods

REFERENCES:

- Boswarthick .D, Elloumi. O and Hersent.O, "M2M communications: A systems approach", 1st edition, John Wiley & Sons, 2012
- 2. Laudon.K, Laudon.J, "Management Information Systems", 14th edition, Pearson Higher Education, 2016
- 3. Rajaraman. A, Leskovec. J, Ullmann. J, "Mining of Massive Data sets", 2nd edition, Dreamtech Press,2016
- 4. Khandpur.R.S, "Handbook of Analytical Instruments", 2nd edition, Tata McGraw Hill Education, 2006
- 5. Edward Carryer.J, "Introduction to Mechatronic Design", 1st edition, Prentice Hall, 2010

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Upon completion of the course, students will be able to

COs	Statements	K-Level
CO1	System Design knowledge of Internet of Things.	Understand
CO2	Ensuring IOT with Security and Privacy as applicable.	Understand
CO3	Implement the M2M Communication protocols in a prototype.	Apply
CO4	Understand computer models of common engineering information types.	Understand
CO5	Understand the basic principle smart manufacturing	Understand

COURSE ARTICULATION MATRIX:

POs COs	PO1	PO2	PO3	PO4	PO5	P06
CO1	1	. 1	3		i ali	1
CO2	1	1	3	-	- '	1
CO3	1	1	3		=.	1
CO4	1	1	3	-	_	1
CO5	1	- 1	3	-	-	1
СО	1	_ 1	3	-	-	1
Correlation levels:	1: Slight (Low)		2: Moderate (Medium)		3: Substantial (High)	

^{*}Role Play / Group Discussions / Debates / Oral Presentations / Poster Presentations / Technical presentations can also be provided. Course Designer can choose any one / two components based on the nature of the course.

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